

THE PAPUA NEW GUINEA UNIVERSITY OF TECHNOLOGY

DEPARTMENT OF ELECTRICAL AND COMMUNICATIONS ENGINEERING

SECOND SEMESTER EXAMINATION (2023)

EE324 ELECTRICAL MACHINES & DRIVES

BEEP 3

TIME ALLOWED: 3 HOURS

INFORMATION FOR STUDENTS:

- You have TEN (10) minutes to read the paper. You must NOT begin writing during this time.
- All answers must be written in the ANSWER BOOK supplied. COMPLETE THE DETAILS REQUIRED ON THE FRONT COVER OF YOUR ANSWER BOOK. DO THIS NOW.
- Drawing instruments and calculators are permitted.
- Answer ALL FIVE (5) questions.
- All questions carry equal marks. Total marks available is 100 marks.
- If you are found cheating in the examination, the penalties specified by the University shall apply.
- Switch OFF all mobile phones.

[2+2+2+2+12 = 20]

QUESTION ONE Marks]

- A. Cite the differences between a *cylindrical* and a *salient-pole* rotor in synchronous generators. [2 marks]
- B. The synchronous speed of a 12-pole generator is 500 rpm. What is the frequency of its operation? [2 marks]
- C. Why is the d-axis reactance larger than the q-axis reactance in a salient-pole alternator? [2 marks]
- D. Explain floating in parallel operation of alternators. [2 marks]
- E. A 48-slot, 8-pole, three-phase synchronous generator is wound using the double-layer winding. [12 marks]

Determine;

- I. the pitch factor,
- II. the distribution factor,
- III. the winding factor,
- IV. the phase voltage, and
- V. the line voltage.

QUESTION TWO

- A. Define *damper winding* and state how it help to minimize *hunting* in synchronous motors? [3 marks]
- B. Why is it necessary to improve the overall power factor of a manufacturing plant? How can this be achieved with a synchronous motor? If a synchronous motor is dedicated to improving the power factor, it is called a _____?
 [5 marks]
- C. A manufacturing plant uses 100 kVA at 0.6 pf lagging under normal operation. A synchronous motor is added to the system to improve the overall power factor. The power required by the synchronous motor is 10 kW.
 - I. Determine the overall power factor when the synchronous motor operates at 0.5pf leading.
 - II. What must be the power factor of the motor to improve the overall power factor to 0.9 lagging?

QUESTION THREE

[20 marks]

The per-phase equivalent circuit parameters of a 208-V, 4-pole, 60-Hz, threephase, Y-connected, induction motor are $R_1 = 0.4 \Omega$, $X_1 = 0.8 \Omega$, $R_2 = 0.3 \Omega$, $X_2 = 0.9 \Omega$, and $X_m = 40 \Omega$. The core loss is 45 W, and the friction and windage loss is 160 W.

When the motor operates at a slip of 5%, determine;

- I. the input current,
- II. the power input,
- III. the air-gap power,
- IV. the power developed,
- V. the power output,
- VI. the shaft torque, and
- VII. the efficiency of the motor.
- VIII. Draw its power-flow diagram

QUESTION FOUR

- A. At what speed does the revolving field rotate in an induction motor? How can it be determined? [3 marks]
- B. What is the rotor frequency when the rotor is; [3 marks]
 - I. locked and
 - II. rotates at 5% slip?
- C. *Rotor Resistance Control* is one method used to control the speed of a three phase induction motor. [5 marks]
 - I. Explain how this is achieved
 - II. State three (3) disadvantages associated with this speed control method
- D. A 120-V, 60-Hz, 6-pole, Δ -connected, three-phase induction motor has a stator impedance of 0.1 + j0.15 Ω /phase and an equivalent rotor impedance of 0.2 + j0.25 Ω /phase at standstill. [11 marks]
 - I. Find the maximum power developed by the motor and the slip at which it occurs.
 - II. What is the corresponding value of the torque developed by the motor?

QUESTION FIVE

A. The rotor speed of a 440-V, 50-Hz, 8-pole, three-phase induction motor is 720 rpm. [9 marks]

Determine;

- I. The synchronous speed
- II. The slip
- III. The rotor frequency
- B. A 2-hp, 120-V, 60-Hz, 4-pole, three-phase, Y-connected, salient-pole, synchronous motor delivers the rated power at 0.8 pf lagging. If $X_d = 2.5\Omega$ /phase and $X_q = 1.7 \Omega$ /phase, and $P_r = 80$ W. [11 marks]

Determine;

- I. The excitation voltage
- II. The power angle
- III. The power developed
- IV. The torque developed
 - v. The efficiency of the motor